

MS05 - MSE05

HYDRAULIC MOTORS



T E C H N I C A L C A T A L O G



INTRODUCTION

Given their optimized and modular design capable of delivering high performance, motors from the MS Classic range have established themselves as a benchmark on the hydraulic motor market.

MS Classic range can be characterized by:

- **Compactness**
- **Optimized cost**
- **Power density**

The MS HighFlow™ motor range has all the qualities that have made the MS Classic range such a success: they are modular and robust, offering performance advantages (speed and power) at the same time.

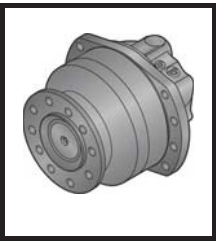
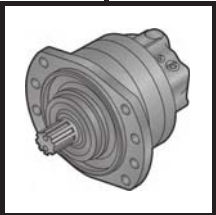
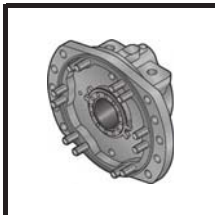
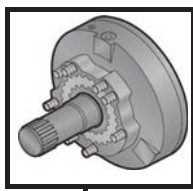
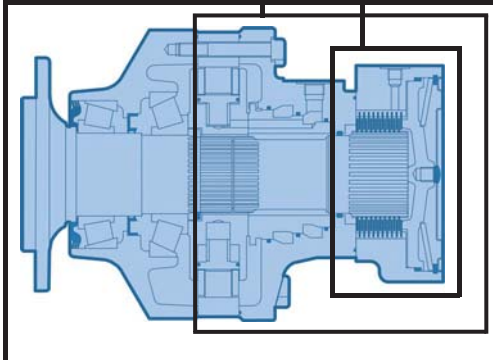
MS HighFlow™ motor range is different by:

- **New closed cover**
- **Integrated exchange valve**
- **New ports geometry**
- **New valving**



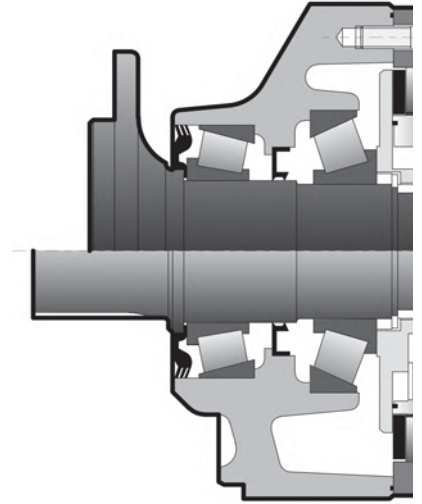


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CHARAC



MS motor working pressure 450 bar [6 526 PSI]
MSE motor working pressure 400 bar [5 801 PSI]

Motor inertia
Noise emissions

MS05-MSE05 HighFlow™

*Max.power	1C motor	50 kW
	2C motor, 1 st displacement	50 kW
	2C motor, 2 nd displacement	30 kW

	C	Motor HighFlow™1C		Motor HighFlow™ 2C	
		Max. speed*		Max. speed*	
		1	2	1	2
		cm³/tr [cu.in/rev.]	cm³/tr [cu.in/rev.]	tr/min[RPM]	tr/min[RPM]
Cams with equal lobes MS05	6	260 [15,9]	130 [7,9]	700	630 630
	8	376 [22,9]	188 [11,5]	520	455 520
	0	468 [28,5]	234 [14,3]	420	370 430
	1	515 [31,4]	258 [15,7]	370	330 400
MSE05	2	560 [34,2]	280 [17,1]	340	300 350
	8	503 [30,7]	252 [15,4]	380	330 370
	0	625 [38,1]	313 [19,1]	300	270 300
	1	688 [42,0]	344 [21,0]	270	240 270
	2	750 [45,7]	375 [22,9]	250	220 240

1 First displacement

2 Second displacement

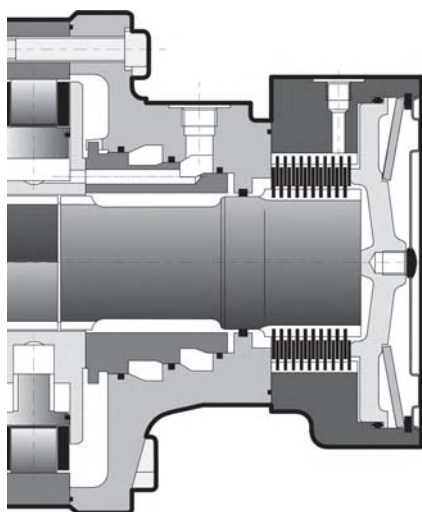
* Based on nominal no-load Δp of 20 bar.



Max. power obtained at max speed, with Peek bushings.



TERISTICS



MS motor working pressure 450 bar [6 526 PSI]
 MSE motor working pressure 400 bar [5 801 PSI]

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

Options

= 0.03 kg.m²
 = 60 dBA

MS05-MSE05 Classic

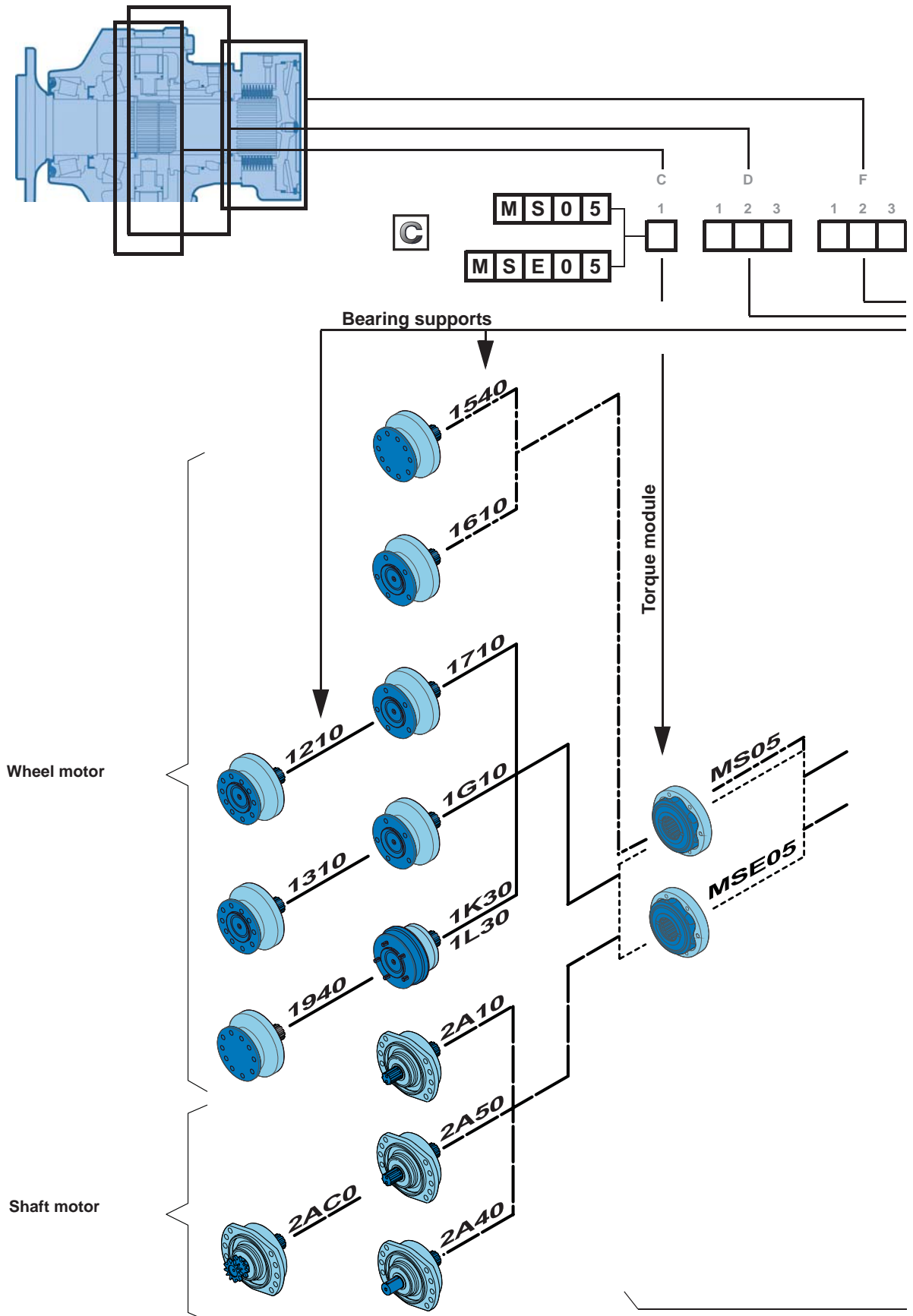
Max. power	1C motor	29 kW
	2C motor preferred	19 kW
	2C motor non-preferred	15 kW

Cams with equal lobes	C	MS05		Classic motor 1C	Classic motor 2C	
		1	2	Max. speed	Max. speed	
		cm ³ /tr [cu.in./rev.]	cm ³ /tr [cu.in./rev.]	tr/min[RPM]	1	2
MS05	6	260 [15,9]	130 [7,9]	300	350	360
	8	376 [22,9]	188 [11,5]	250	310	320
	0	468 [28,5]	234 [14,3]	210	260	275
	1	515 [31,4]	258 [15,7]	200	240	250
	2	560 [34,2]	280 [17,1]	180	220	230
MSE05	8	503 [30,7]	252 [15,4]	230	250	300
	0	625 [38,1]	313 [19,1]	190	220	250
	1	688 [42,0]	344 [21,0]	170	180	210
	2	750 [45,7]	375 [22,9]	155	160	190

- 1 First displacement
- 2 Second displacement

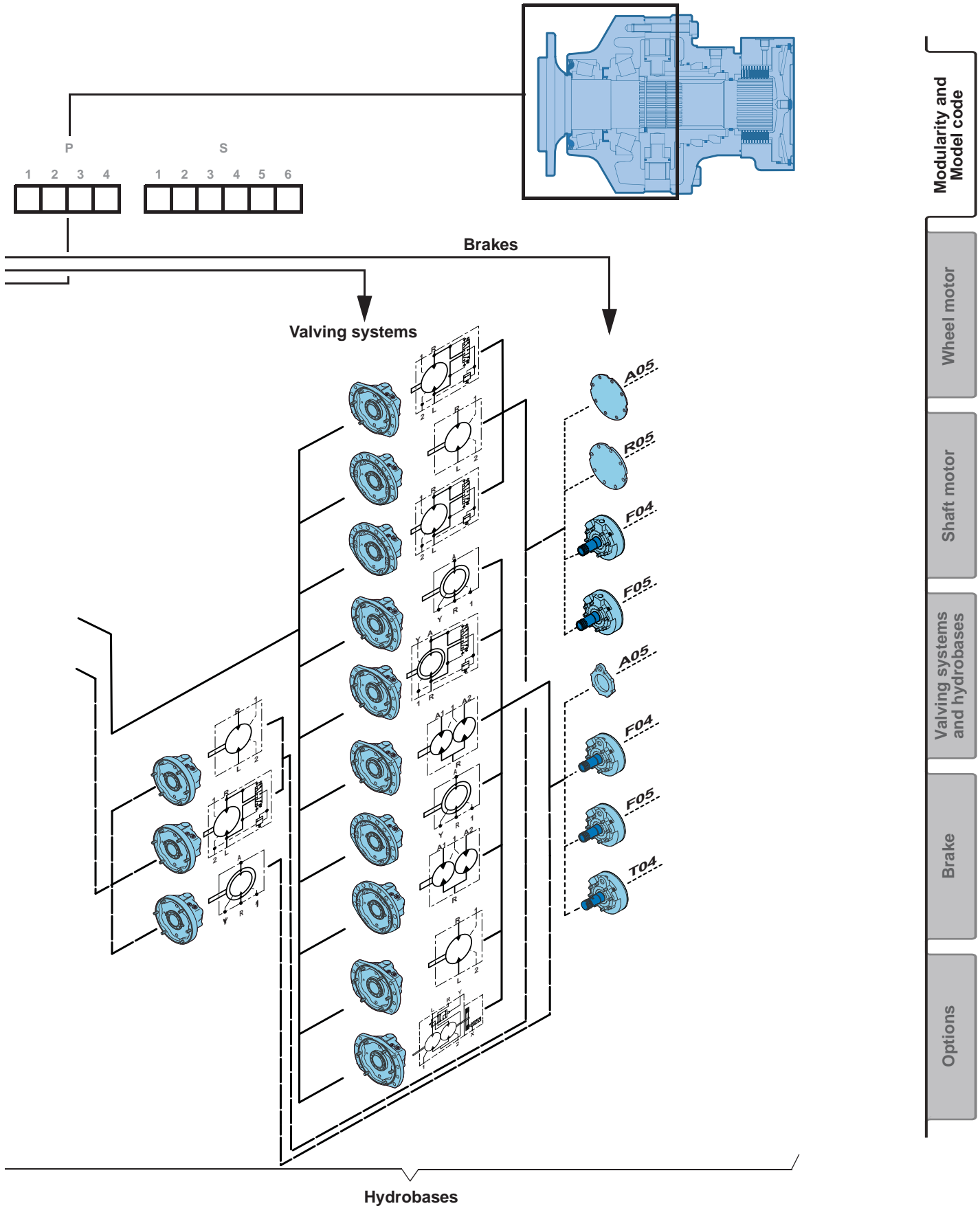


MODUL



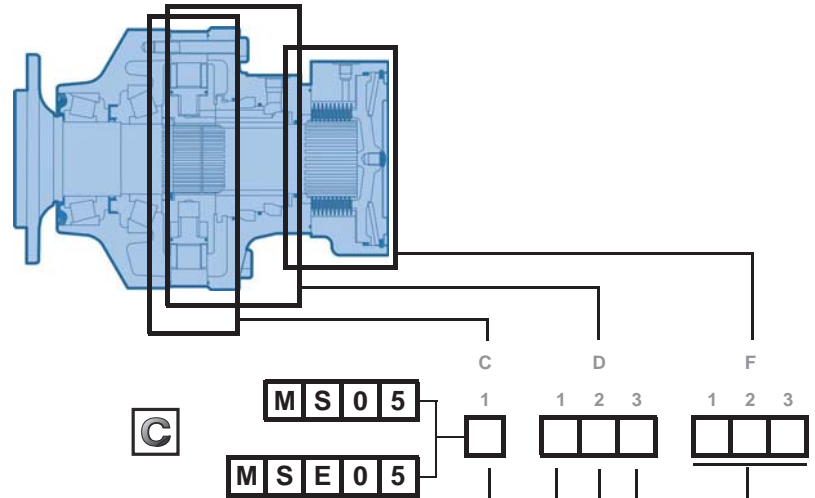


ARITY





MODEL



C1
Cam ring type

	1 displacement 2 displacements		
	cm ³ /tr [cu.in/rev.]		
MS05	260 [15.9]	130 [7.9]	6
	376 [22.9]	188 [11.5]	8
	468 [28.6]	234 [14.3]	0
	515 [31.4]	258 [15.7]	1
MSE05	560 [34.2]	280 [17.1]	2
	503 [30.7]	251 [15.3]	8
	625 [38.1]	313 [19.1]	0
	688 [42.0]	344 [21.0]	1
	750 [45.7]	375 [22.9]	2

D2
Valving cover

Classic motor	Without mounting	1	4	-
	Lug fixing	2	-	E
	Horseshoe fixing	8	9	G
High Flow™ motor	Without mounting	B	L	-
	Lug fixing	C	N	-

D1
Valving type

1-displacement valving	1
2-displacement symmetrical valving	A Ratio 2
	B Ratio <2
	C Ratio >2
2-displacement & Twin-Lock™ valving (Clockwise)	D Ratio 2
	E Ratio <2
	F Ratio >2
2-displacement & Twin-Lock™ valving (Counterclockwise)	G Ratio 2
	H Ratio <2
	J Ratio >2

D3
Connection type

ISO 11926-1 connection	A
ISO 1179-1 connection	3
ISO 9974-1 connection	4
ISO 6149-1 connection	8

F1-F3
Rear brake

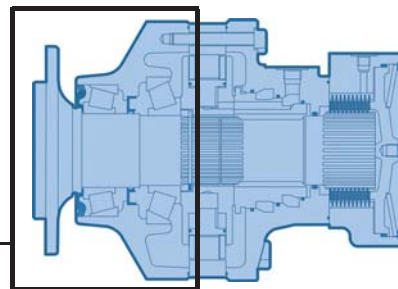
Without brake (simple plate)				A 0 5
Without brake (closed cover)*				M 0 5
Brake	Bearing mounting or valving cover mounting	Parking brake	Clipped environmental cover	F 0 4
			Screwed environmental cover**	T 0 4
Without brake (reinforced plate)				R 0 5

* Mandatory for High Flow™ valving without brake

** Only with HighFlow™ valving



CODE



P1 Front unit

0	Without bearing support
1	Without mounting
2	Lug mounting

P2 Bearing support

0	Without shaft
2	10 x Ø18 on Ø140
3	5+3 x Ø18 on Ø140
5	10 x M12 on Ø100
6	5 x Ø18 on Ø140
7	6 x Ø20 on Ø205
9	10 x M12 on Ø100
F	Support without drum brake
G	
K	Drum brake (250 x 60)
L	
A	For male shaft bearing support

P3 Shaft type

1	Without studs
2	With studs + nuts
3	With studs
4	M threaded holes

Male shafts

1	NF E 22141 splines
4	Cylindrical with key
5	DIN 5480 splines
C	Dual sprocket for chain

P4 Drum brake (250 x 60)

7	Without cable	10 x M14 on Ø140
8	Right-hand cable outlet	
9	Left-hand cable outlet	
A	Without cable	6 x M18 on Ø205
B	Right-hand cable outlet	
C	Left-hand cable outlet	

Options

0	Without Options or Adaptations
1	Fluorinated elastomer seals
2	T4 speed sensor (without rotation direction)
3	Brake environmental cover without plug
5	Drainage
6	Industrial bearing support
7	Diamond™
8	Predisposition for speed sensor
A	Hollow shaft
B	Drain on the bearing support
C	Abrasive environment
D	Special paint or no paint
E	Reinforced sealing
G	Special wheel rim mounting
H	High efficiency
J	Surface heat treatment of the shaft
M	High speed
Q	TD speed sensor (two phase shifted frequencies)
S	TR speed sensor (digital rotation direction)
T	Soft Shift™

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

Options



Methodology :

This document is intended for manufacturers of machines that incorporate Poclain Hydraulics products. It describes the technical characteristics of Poclain Hydraulics products and specifies installation conditions that will ensure optimum operation. This document includes important comments concerning safety. They are indicated in the following way:



Safety comment.

This document also includes essential operating instructions for the product and general information. These are indicated in the following way:



Essential instructions.



General information .



Information on the model number. Information on the model code.



Weight of component without oil.



Volume of oil.



Units.



Tightening torque.



Screws.



Information intended for Poclain-Hydraulics personnel.

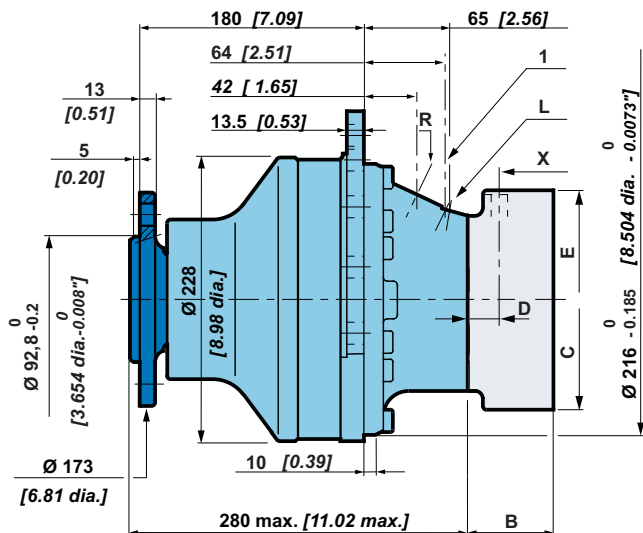
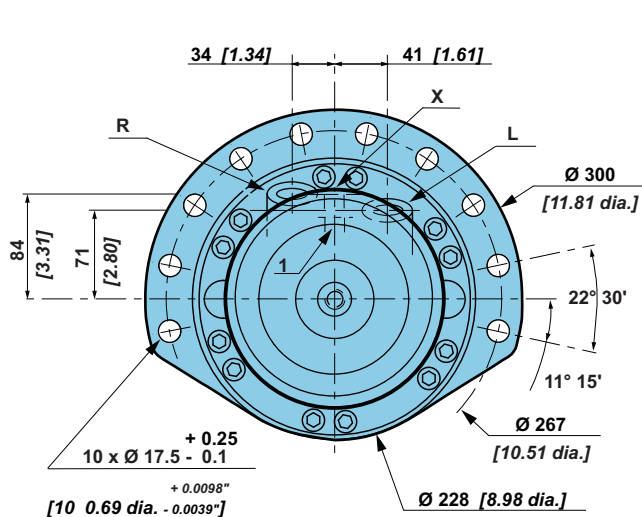
The views in this document are created using metric standards.

The dimensional data is given in mm and in inches (inches are between brackets and italic>



Dimensions for Classic (1210) 1-displacement motor

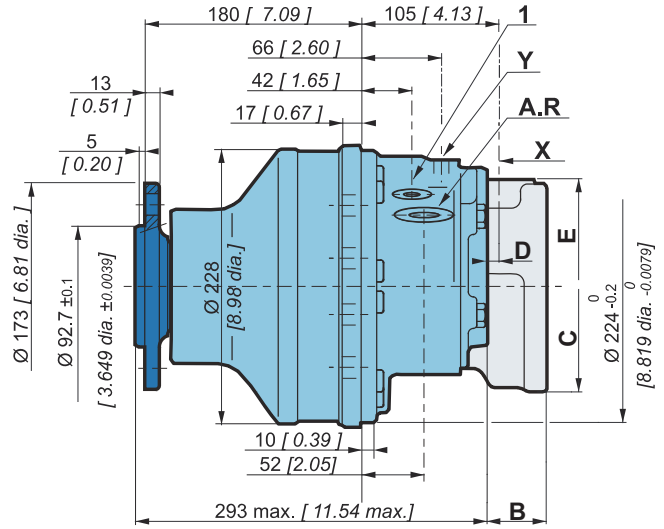
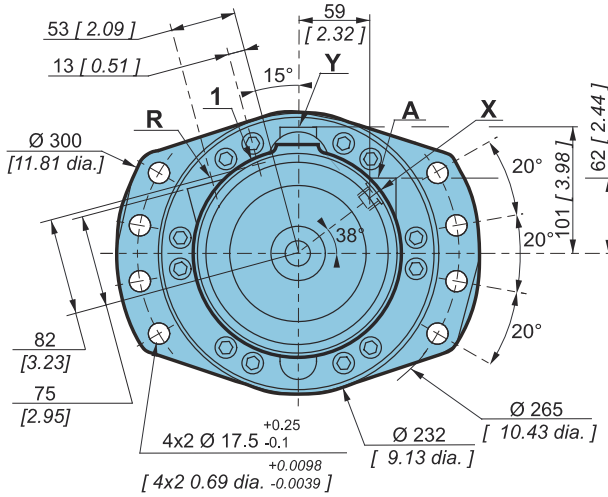
	40 kg [88 lb]	50 kg [110 lb]
	1,00 L [60 cu.in]	1,00 L [60 cu.in]



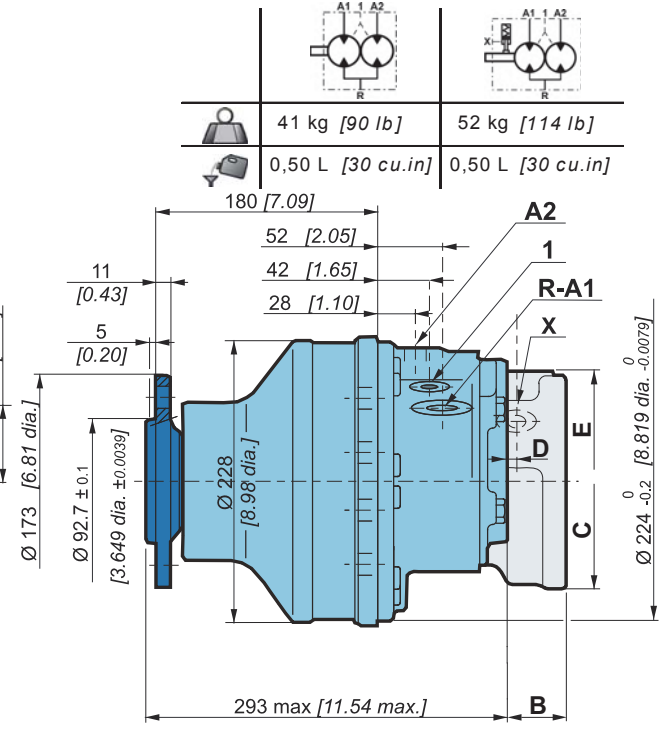
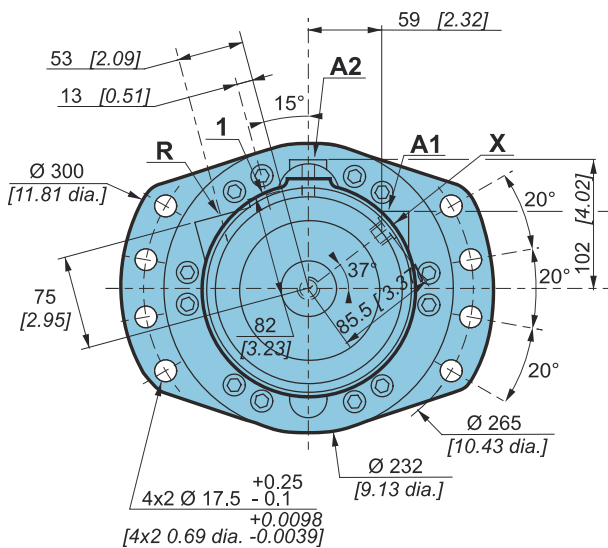


WHEEL MOTOR CLASSIC

Dimensions for Classic (1210) 2-displacement motor



Dimensions for Classic (1210) Twin-Lock™



	41 kg [90 lb]	52 kg [114 lb]
	0,50 L [30 cu.in.]	0,50 L [30 cu.in.]

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

Options

	C	F 0 4	F 0 5
B	69,1 [2,72]	64,0 [2,52]	
C	Ø216 [8,50 dia.]	Ø218 [8,56 dia.]	
D	23,0 [0,91]	23,0 [0,91]	
E	85,5 [3,37]	85,5 [3,37]	

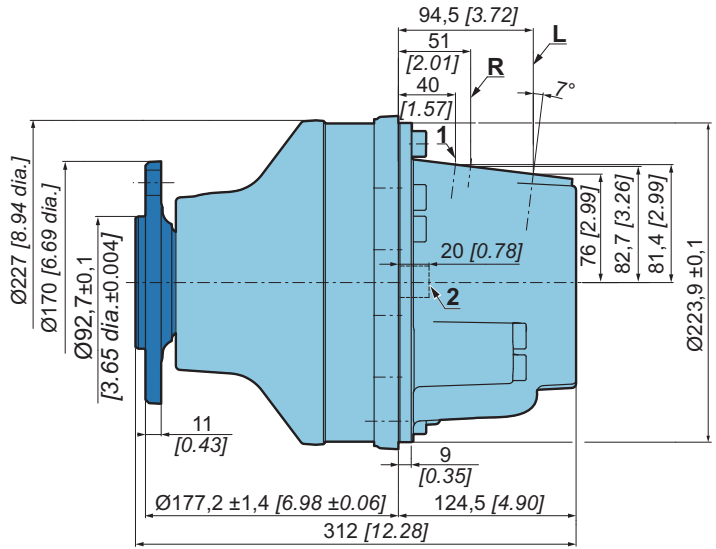
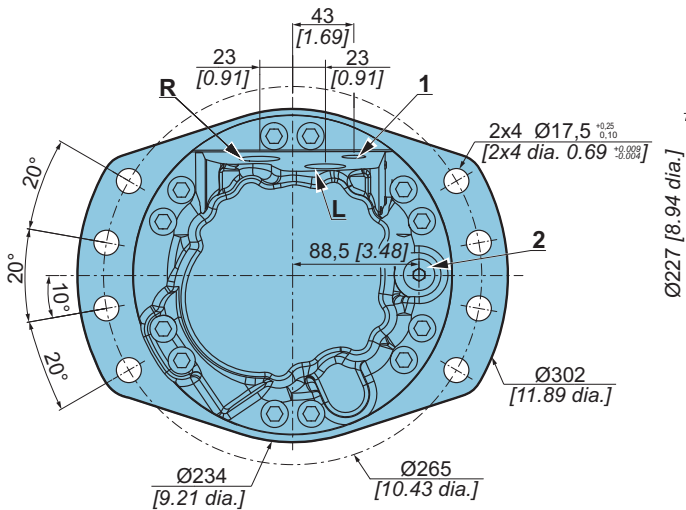
Also see "Brake" section (thumbnail opposite).

Also see 'Valving systems and hydrobases' section (thumbnail opposite).



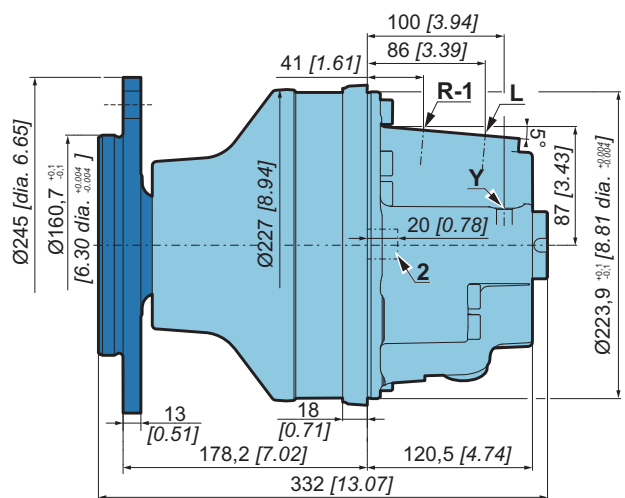
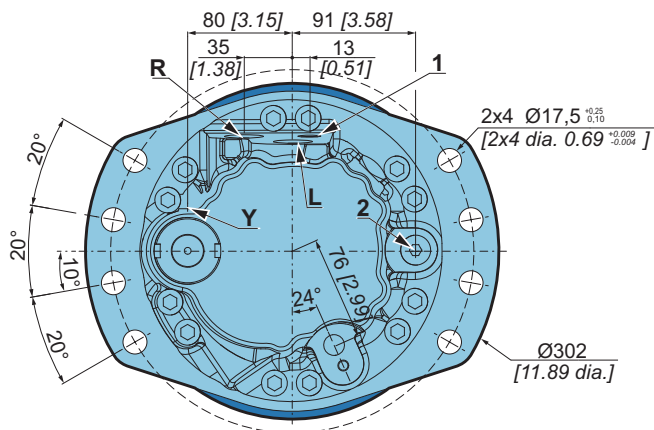
WHEEL MOTOR HIGH FLOW™

Dimensions for HighFlow™ (1210) 1-displacement motor



	41 kg [90 lb]
	0,50 L [30 cu.in]

Dimensions for HighFlow™ (1710) 2-displacement motor

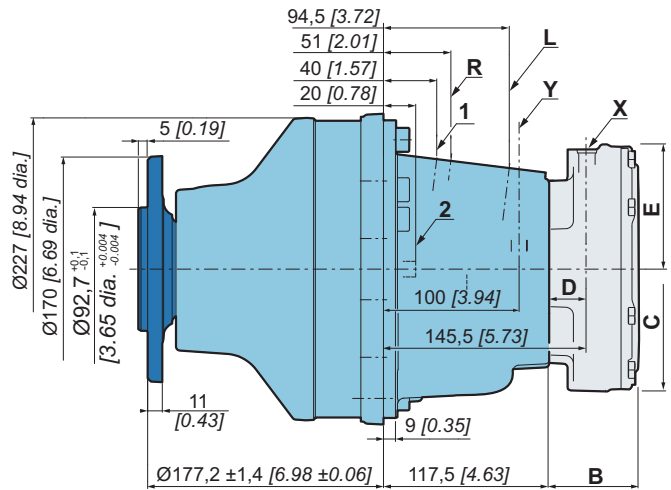
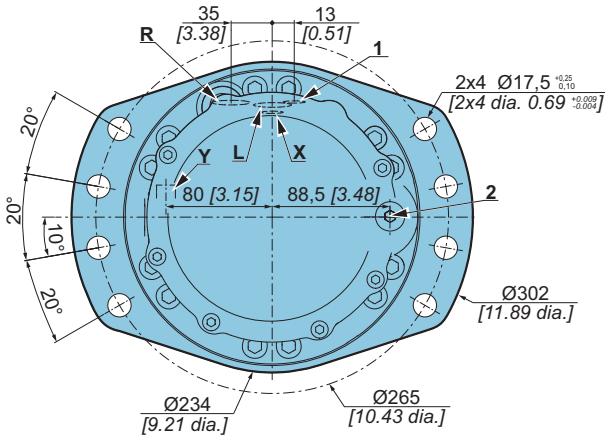
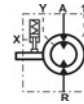


	41 kg [90 lb]
	0,50 L [30 cu.in]



Dimensions for HighFlow™ (1210) 2-displacement motor

	60 kg [132 lb]
	0,50 L [30 cu.in]



	C	T 0 4
	B	68,5 [2,70]
	C	Ø200 [7,87 dia.]
	D	28,0 [1,10]
	E	87,5 [3,44]

Also see "Brake" section (thumbnail opposite).

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

Options



Bearing support for Classic and HighFlow™ motor

	C				D			F			P				S					
	MS05				MSE05															
	1 1 2 3				1 2 3			1 2 3 4			1 2 3 4				1 2 3 4 5 6					
C	A	B	C	D	E	N	Wheel rim mountings	L												
	mm [in]	mm [in]	mm [in]	mm [in]	mm [in]	mm [in]		mm [in]												
1 2 1 0 1 2 3 4 P	Ø 92,7 [3,65 dia.]	Ø 140 [5,51 dia.]	Ø 170 [6,69 dia.]	178,6 [7,03]	Ø 228 [8,98 dia.]	Ø 18 [0,71 dia.]	10 x M14x1.5	11 [0,43]												
1 7 1 0 1 2 3 4 P	Ø 160,7 [6,33 dia.]	Ø 205 [8,07 dia.]	Ø 245 [9,65 dia.]	178,5 [7,03]	Ø 228 [8,98 dia.]	Ø 20 [0,79 dia.]	6 x M18x1.5	14 [0,55]												
1 3 1 0 1 2 3 4 P	Ø 95,7 [3,77 dia.]	Ø 140 [5,51 dia.]	Ø 180 [7,09 dia.]	145,4 [5,72]	Ø 228 [8,98 dia.]	Ø 18 [0,71 dia.]	5 x M14x1.5	10,5 [0,41]												
1 6 1 0 1 2 3 4 P	Ø 92,7 [3,65 dia.]	Ø 140 [5,51 dia.]	Ø 180 [7,09 dia.]	145,4 [5,72]	Ø 228 [8,98 dia.]	Ø 18 [0,71 dia.]	5 x M14x1.5	10,5 [0,41]												
1 5 4 0 1 2 3 4 P	-	Ø 100 [3,94 dia.]	Ø 120 h7 [4,72 dia.]	145,4 [5,72]	Ø 228 [8,98 dia.]	10 x M12x1.75	-	11,3 [0,44]												
1 9 4 0 1 2 3 4 P	-	Ø 100 [3,94 dia.]	Ø 120 h7 [4,72 dia.]	178,7 [7,04]	Ø 228 [8,98 dia.]	10 x M12x1.75	-	11,25 [0,44]												
1 K 3 0 1 L 3 0 1 2 3 4 P	Ø 92,7 [3,65 dia.]	Ø 140 [5,51 dia.]	Ø 276 [10,87 dia.]	209 [8,23]	Ø 228 [8,98 dia.]	Ø 18 [0,71 dia.]	10 x M14x1.5	30 [1,18]												
	Ø 160,7 [6,33 dia.]	Ø 205 [8,07 dia.]	Ø 276 [10,87 dia.]	209 [8,23]	Ø 228 [8,98 dia.]	Ø 20 [0,79 dia.]	6 x M18x1.5	35 [1,38]												
	Also see "Brake" section (thumbnail opposite).																			
1 G 1 0 1 2 3 4 F	Ø 92,7 [3,65 dia.]	Ø 140 [5,51 dia.]	Ø 170 [6,69 dia.]	201,2 [7,92]	Ø 228 [8,98 dia.]	Ø 18 [0,71 dia.]	10 x M14x1.5	-												
1 F 1 0 1 2 3 4 F	Ø 160,7 [6,33 dia.]	Ø 205 [8,07 dia.]	Ø 245 [9,65 dia.]	201,2 [7,92]	Ø 228 [8,98 dia.]	Ø 20 [0,79 dia.]	6 x M18x1.5	-												



The supports in gray must not be assembled with an MSE hydrobase.



For stronger bearings, consult with your Poclair Hydraulics application engineer.

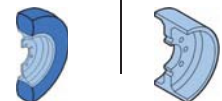
Studs

		P	C min.	C max.	D	Class		
		mm [in]	mm [in]	mm [in]	mm [in]		N.m [lb.ft]	N.m [lb.ft]
Various studs	M14x1.5	45 [1.77]	5 [0.20]	18 [0.71]	16.5 [0.65]	12.9	200 [147.5]	250 [184.4]
	M14x1.5	50 [1.97]		23 [0.91]				
	M14x1.5	62 [2.44]		33 [1.30]				
	M18x1.5	65 [2.56]		28 [1.10]				
Screws	M12x1.75	-	-	-	-	10.9	120 [88.5]	120 [88.5]
	1/2"-20 UNF	-	-	-	-	8.8	-	-

(*) The tightening torques are given for the indicated loads.

(1) **Wheel rim** : Suggested tightening torque for wheel rim mountings (Re steel disc > 240 N/mm² [$>34\ 800\ \text{PSI}$]).

(2) **Standard** : Suggested tightening torque in other cases (Re steel flange > 360 N/mm² [$>52\ 215\ \text{PSI}$]).



See generic installation motors N°801478197L.



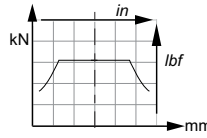
Load curves for Classic and HighFlow™ motor

Permissible radial loads

Test conditions :

Static : 0 tr/min [0 RPM] 0 bar [0 PSI]

Dynamic : 0 tr/min [0 RPM], code 0 displacement, without axial load at max. torque



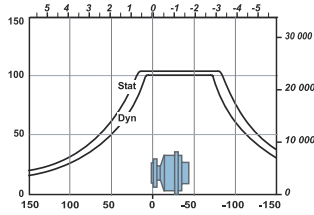
Service life of bearings

Test conditions :

L : Millions B10 revolutions at 150 bars (average pressure), with 25 cSt fluid, code 0 displacement, without axial load.

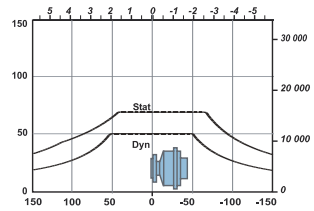
1	2	1	0
1	2	3	4

P



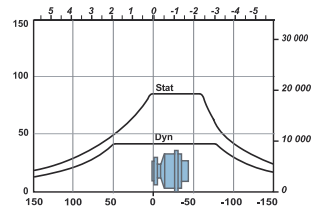
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1	6	1	0
1	2	3	4

P



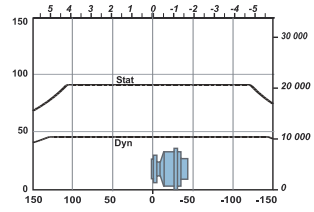
1	5	4	0
1	2	3	4

P



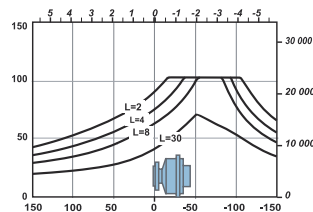
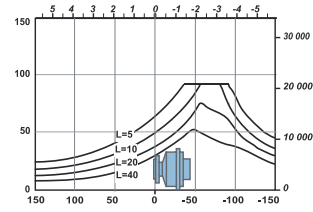
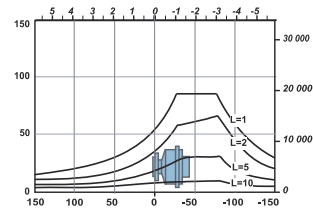
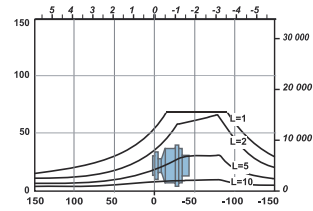
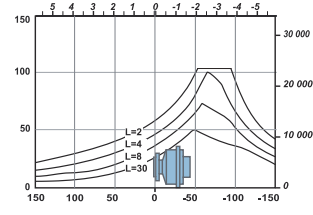
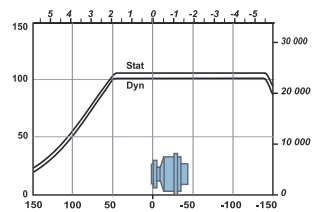
1	9	4	0
1	2	3	4

P



1	7	1	0
1	F	1	0
1	G	1	0
1	K	2	0
1	L	2	0
1	2	3	4

P



Modularity and Model code

Wheel motor

Shaft motor

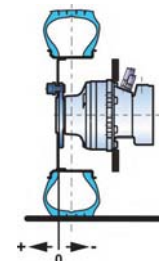
Valving systems and hydrobases

Brake

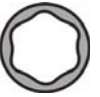
Options



The service life of the components is influenced by the pressure. You must check that the combination of forces applied (Axial load / Radial load) is compatible with the permissible loads for the components, and that the resulting service lives of these components complies with the application's specifications. For an accurate calculation, consult your Poclain Hydraulics application engineer.

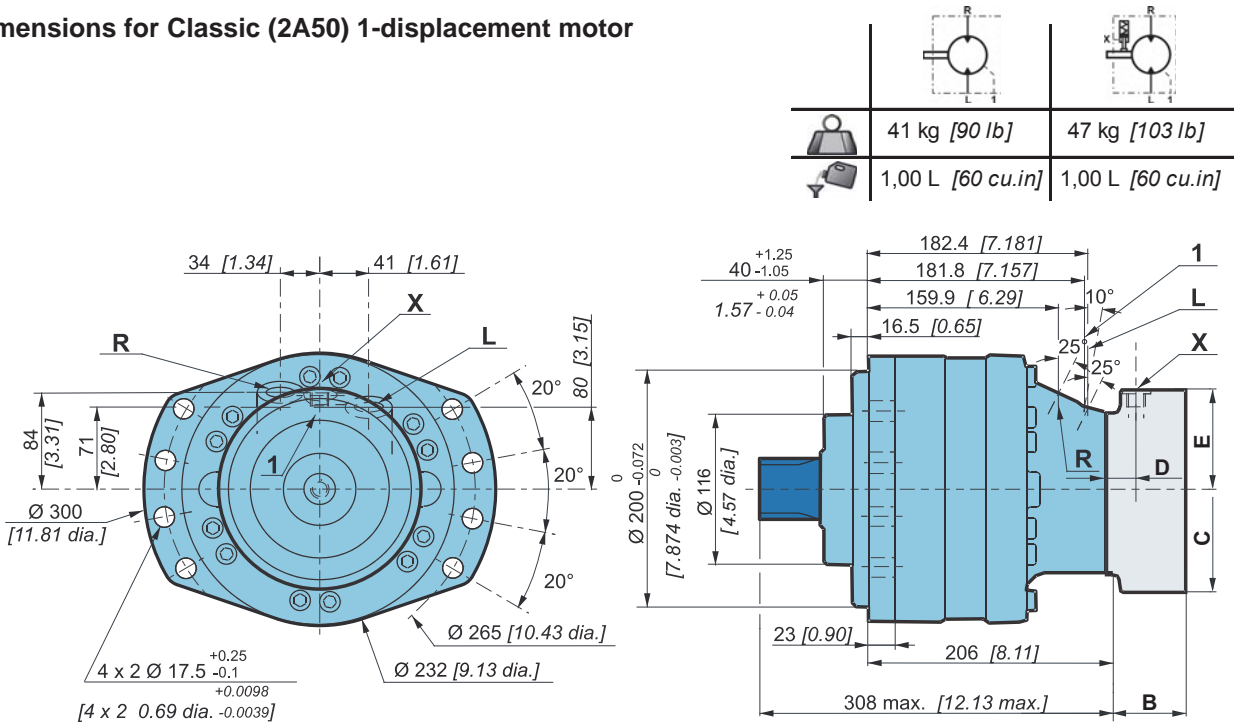




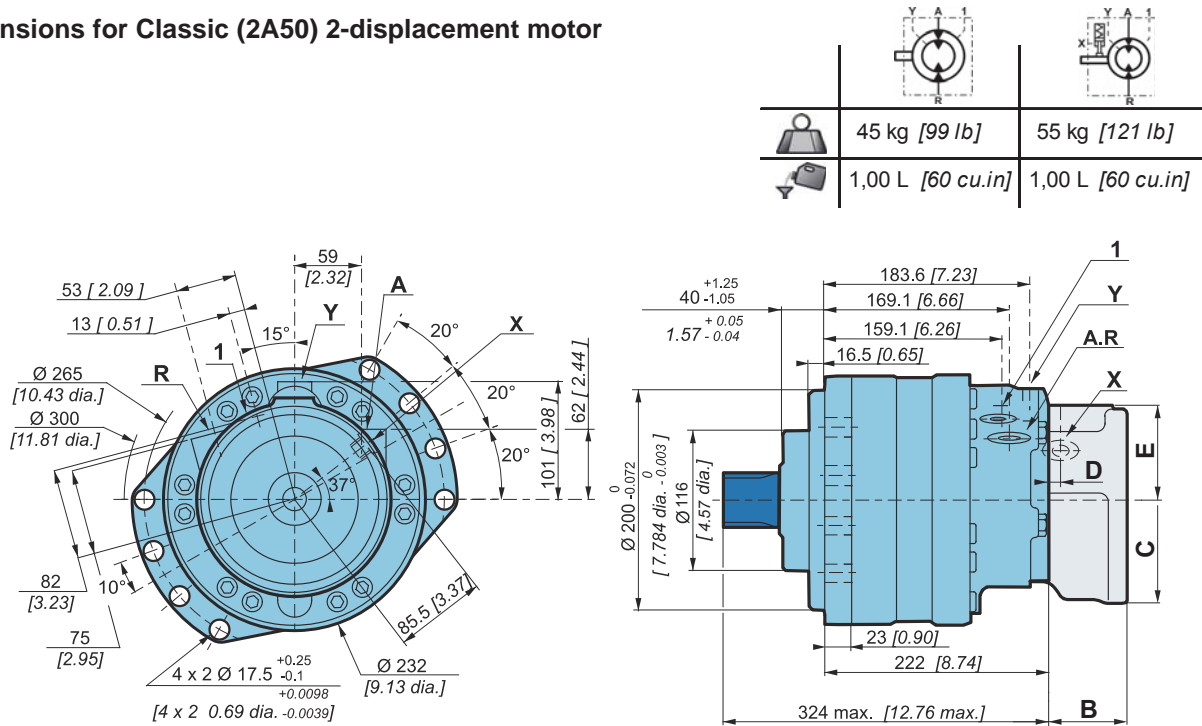


SHAFT MOTOR CLASSIC

Dimensions for Classic (2A50) 1-displacement motor



Dimensions for Classic (2A50) 2-displacement motor



	C	F 0 4	F 0 5
B	69,1 [2,72]	64,0 [2,52]	
C	Ø216 [8,50 dia.]	Ø218 [8,56 dia.]	
D	23,0 [0,91]	23,0 [0,91]	
E	85,5 [3,37]	85,5 [3,37]	

i Also see "Brake" section (thumbnail opposite).

i Also see 'Valving systems and hydrobases' section (thumbnail opposite).

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

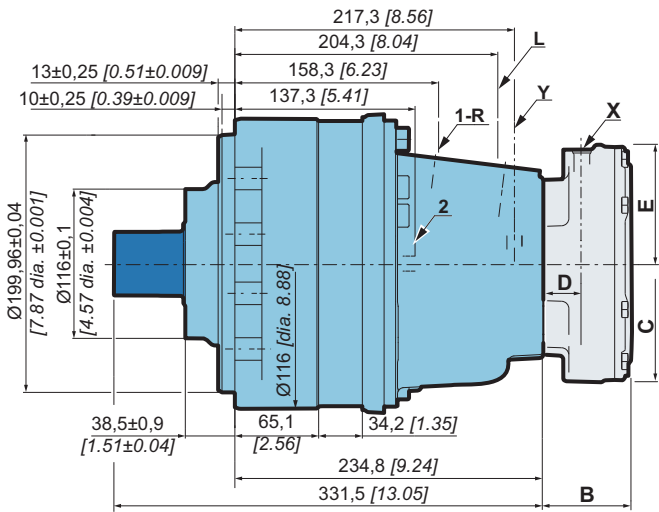
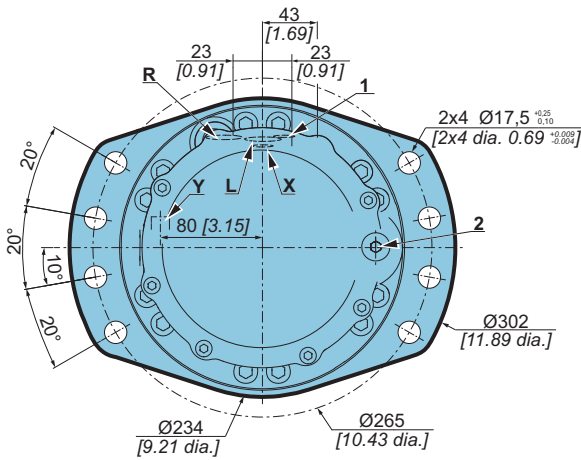
Options



SHAFT MOTOR - HIGHFLOW™ MOTOR

Dimensions for HighFlow™ (2A50) 1-displacement motor

	55 kg [121 lb]	64 kg [141 lb]
	1,00 L [60 cu.in]	1,00 L [60 cu.in]

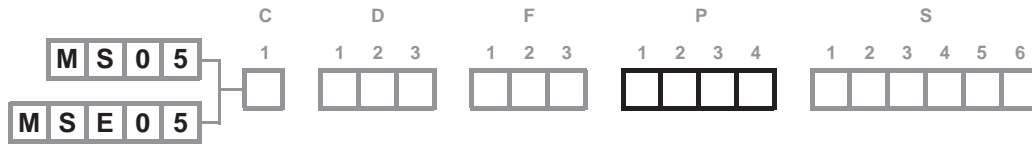


C	T 0 4
B	68,5 [2,70]
C	Ø200 [7,87 dia.]
D	28,0 [1,10]
E	87,5 [3,44]

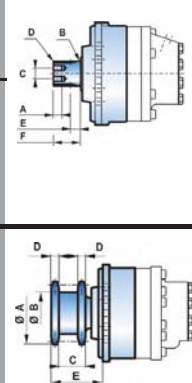
Also see "Brake" section (thumbnail opposite).



Support type for Classic and HighFlow™ motor



C				A	B	C	D	E	F	G		
NF E22-141 splines												
2 A 1 0				Nominal Ø	50 [1,97]	15	R 2,3	23,8	2 x M10	20	54	-
1 2 3 4				Module	1,667	[0,59]	[R 0,09]	[0,94]		[0,79]	[2,13]	
P				Number of teeth	28							
DIN 5480 splines												
2 A 5 0				Nominal Ø	55 [2,17]	15	R 2,3	23,8	2 x M10	23	60	-
1 2 3 4				Module	3	[0,59]	[R 0,09]	[0,94]		[0,91]	[2,36]	
P				Number of teeth	17							
ANSI B29-1 or ISO 606 pinion												
2 A C 0				Chain no.	100	158,2	106	49	17,6	117	-	-
1 2 3 4				Number of teeth	14	[6,23]	[1,97]	[1,91]	[0,69]	[4,61]		
P				Pitch	31,75							
				Pitch Ø	142,7 [5,62]							

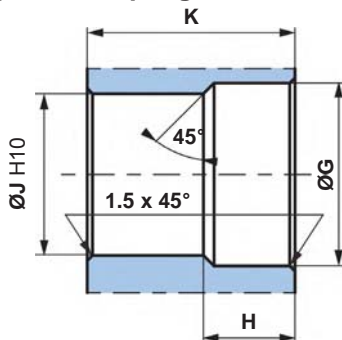


Modularity and Model code
Wheel motor
Shaft motor



Also see 'Valving systems and hydrobases' section (thumbnail opposite).

Spined coupling



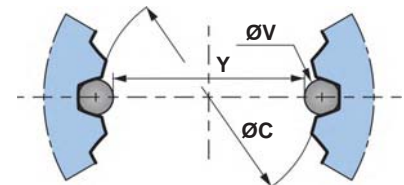
Standard NF E 22-141

Pressure angle 20°.
Centering on flanks.
Slide fit (7H quality).

Standard DIN 5480

Pressure angle 30°.
Centering on flanks.
Slide fit (7H quality).

N : Nominal Ø.
Mo : Module.
Z : Number of teeth.



Valving systems and hydrobases
Brake

C				Ø G	H	Ø J	K	N	Mo	Z	Offset	Ø C (H10)	Ø V	Y	Tolerance µm [µin]
2 A 1 0				51	23	46,7	53	50	1,667	28	+1,333	46,7	3,333	43,446	+ 86 / 0
1 2 3 4				[2,01]	[0,91]	[1,84]	[2,09]	[1,97]			[+0,052]	[1,84]	[0,1312]	[1,71]	[+3.386 / 0]
P															
2 A 5 0				56,5	24	49	59	55	3	17	+0,35	49	5,25	43,807	+ 78 / 0
1 2 3 4				[2,22]	[0,94]	[1,93]	[2,32]	[2,17]			[+0,0138]	[1,93]	[0,21]	[1,7247]	[+3.071 / 0]
P															

General tolerances : ± 0.25 [±0.0098].

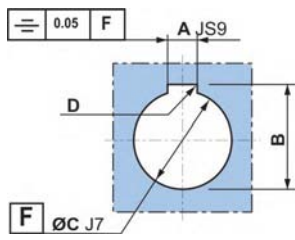
Material: Ex: 42CrMo4.

Hardening treatment to obtain R = 800 to 900 N/mm² [R = 116 030 to 130 533 PSI].

Options



Cylindrical keyed coupling



C				A	B	Ø C	D
2	A	4	0	14 ± 0.021 [0,55] [± 0.0008]	+ 0,2 53 0 [2,07] + 0,007 0	50 [1,97]	0,5 [0,02]
1	2	3	4	P			

Torque limitation : 800 N.m [590 lb.ft]

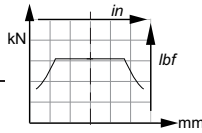
Load curves for Classic and HighFlow™ motor

Permissible radial loads

Max. permissible loads: 0 tr/min [0 RPM]; 0 bar [0 PSI]

Continuous permissible loads:

> 0 tr/min [> 0 RPM]; 275 bar [3 988 PSI].

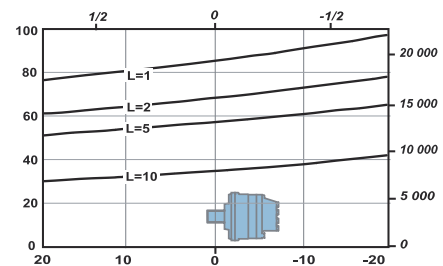
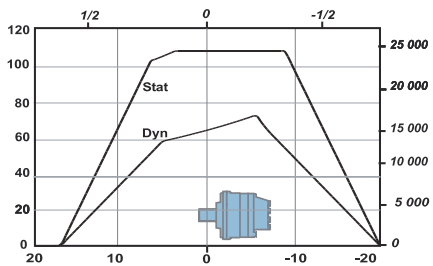


Service life of bearings

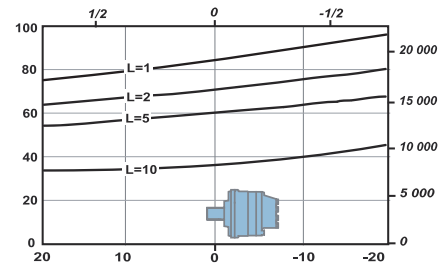
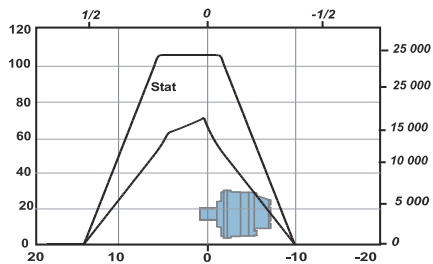
Test conditions :

L : Millions B10 revolutions at 150 bars (average pressure), with 25 cSt fluid, code 0 displacement, without axial load.

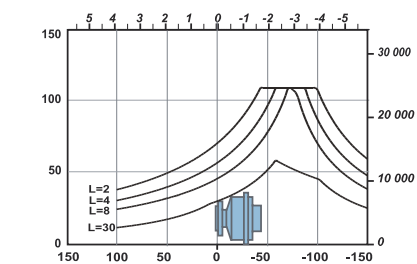
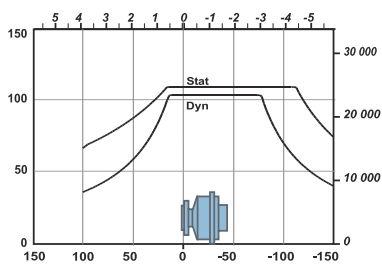
2	A	5	0
1	2	3	4
P			



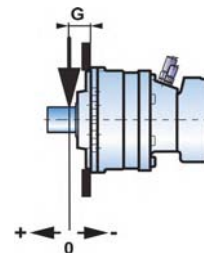
2	A	1	0
2	A	4	0
1	2	3	4
P			



2	A	C	0
1	2	3	4
P			



The service life of the components is influenced by the pressure. You must check that the combination of forces applied (Axial load / Radial load) is compatible with the permissible loads for the components, and that the resulting service lives of these components complies with the application's specifications. For an accurate calculation, consult your Poclair Hydraulics application engineer.

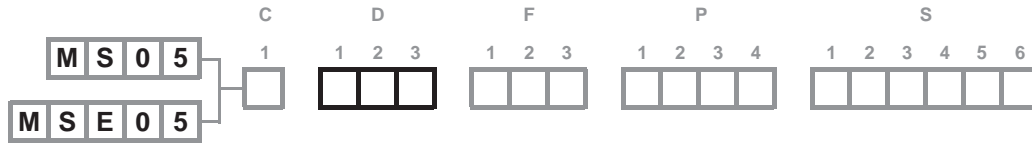


C				G
2	A	1	0	77,25 [3,04]
2	A	5	0	81,75 [3,22]
2	A	C	0	61,45 [2,42]

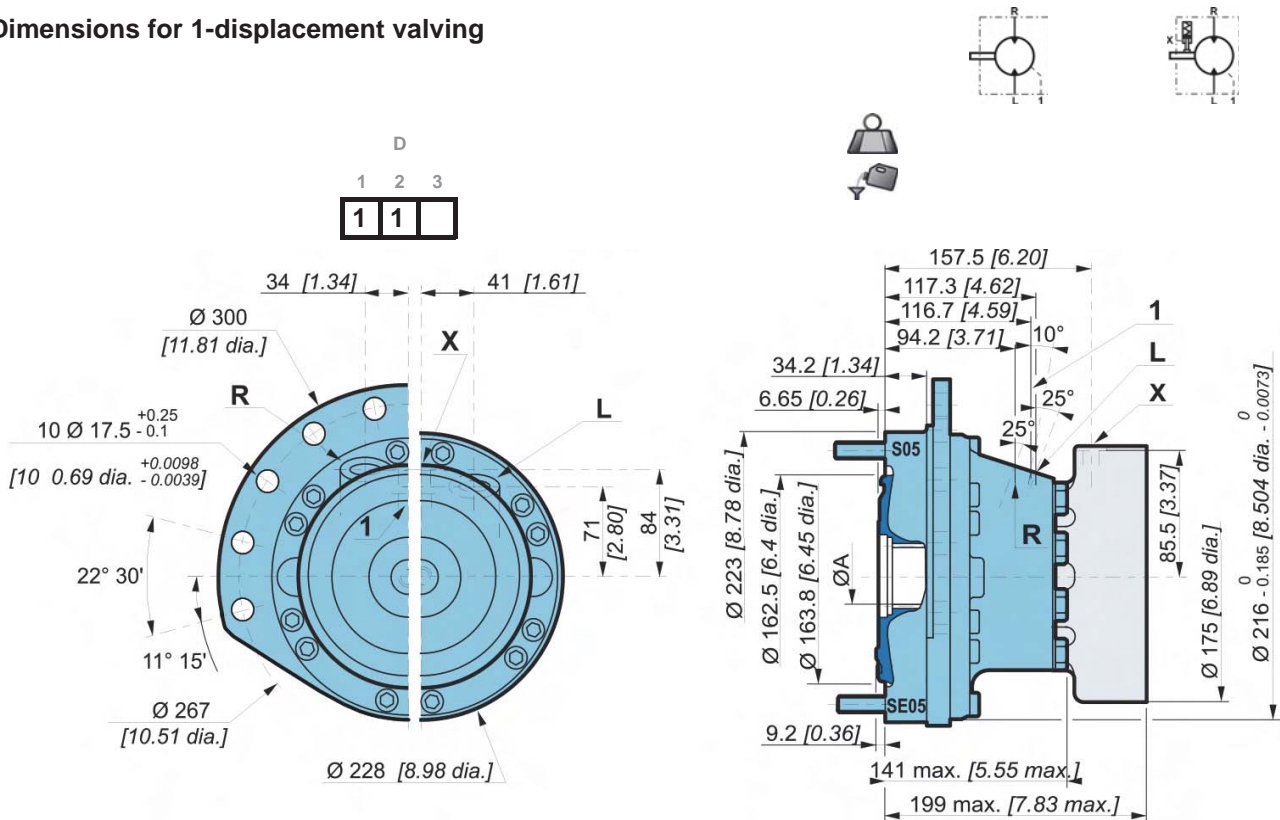


VALVING SYSTEMS AND HYDROBASES

for Classic motor on demand for HighFlow™ motor



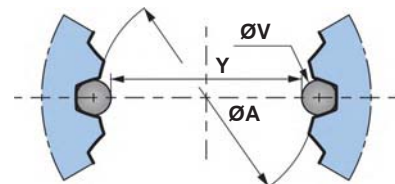
Dimensions for 1-displacement valving



Cylinder block splines

(as per standard NF E22-141)

ØA	Module	Z	Dimension on 2 pins	
			Y	ØV
50 [1,968]	1,667	28	43,446 [1,710]	3,33 [0,131]



You are advised to have the installation validated by your Poclain Hydraulics application engineer before using the hydraulic unit in an application.



We must provide you with a detailed plan of the interface for any hydraulic unit use, consult your Poclain Hydraulics sales engineer.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

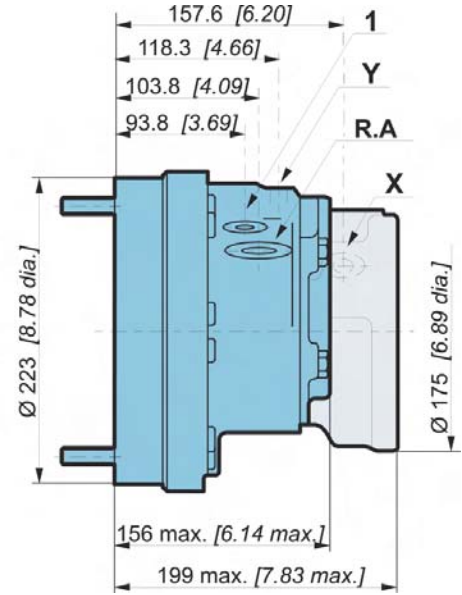
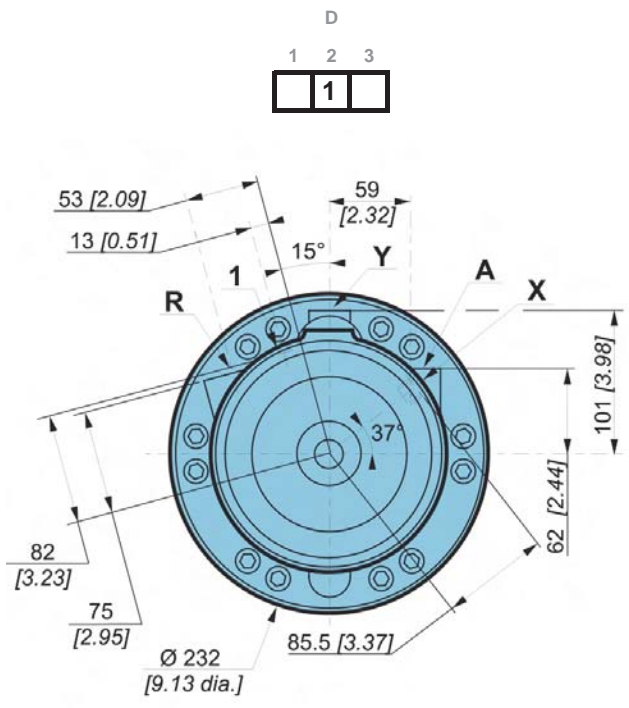
Brake

Options

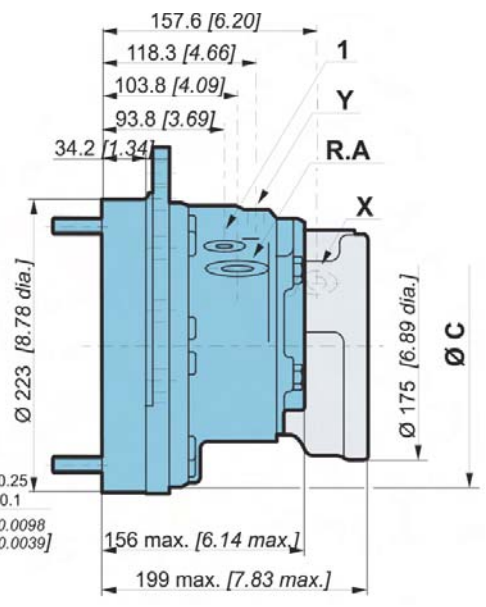
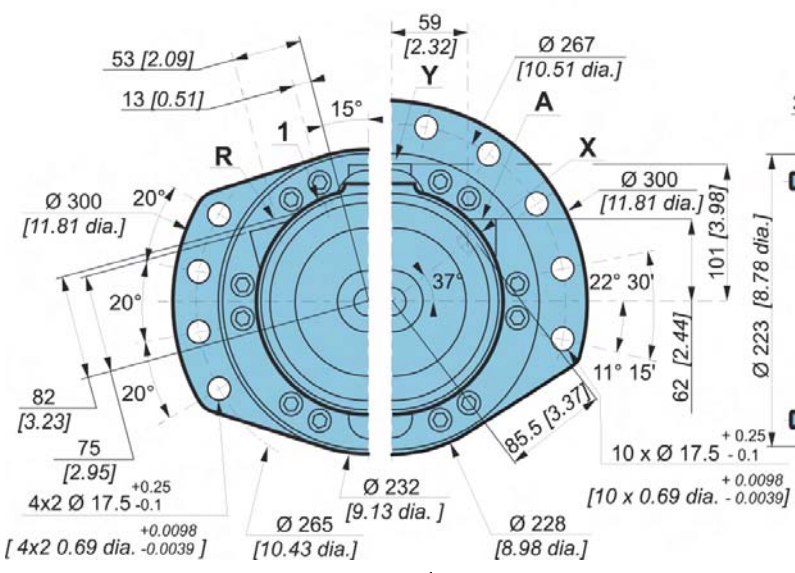


Dimensions for 2-displacement valving

	27,6 kg [61 lb]	35,2 kg [77 lb]
	0,50 L [30 cu.in]	1,00 L [60 cu.in]



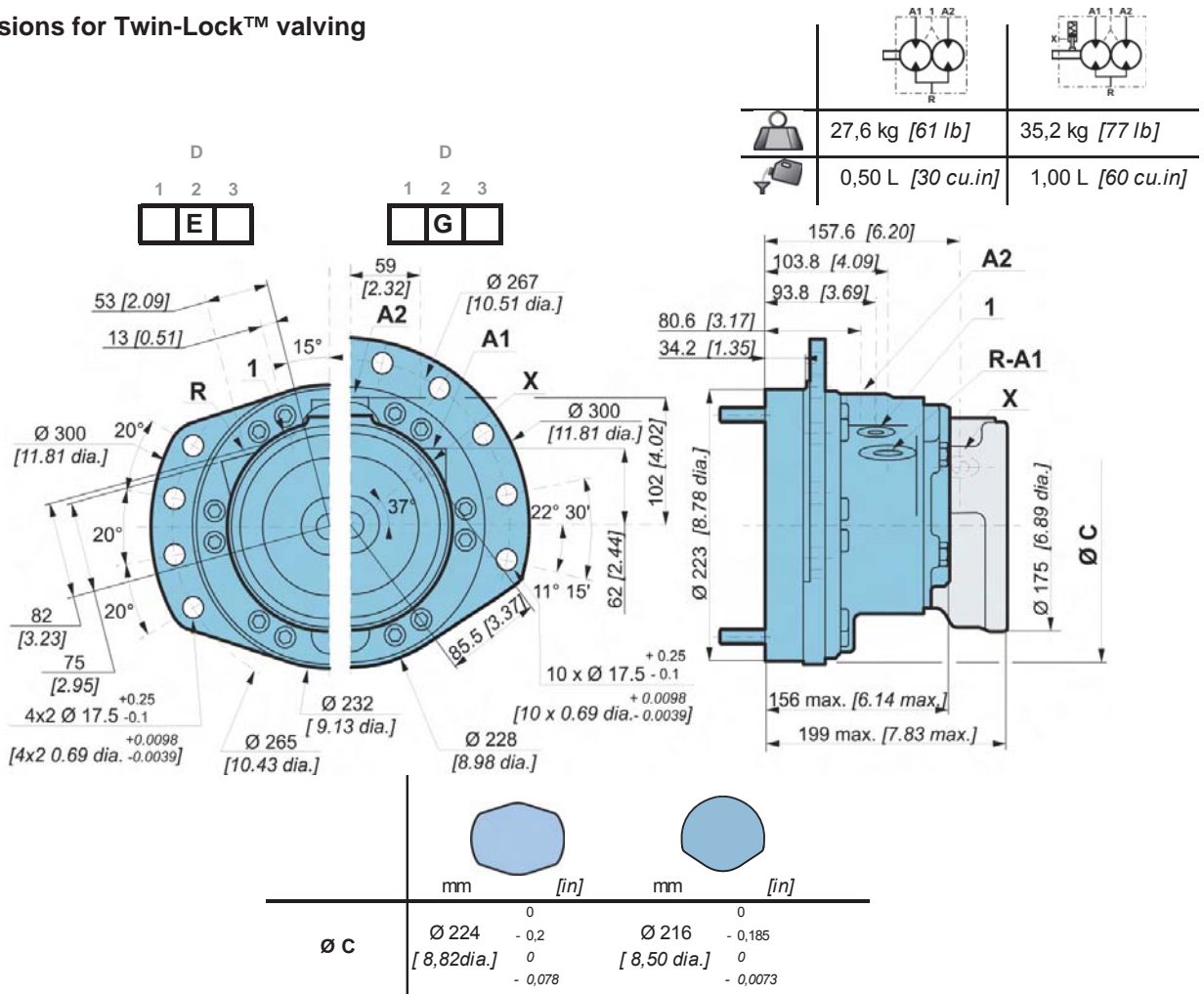
D	1	2	3	D	1	2	3
	1				8		



	mm [in]	mm [in]
Ø C	Ø 224 -0.2 [8,82 dia.]	Ø 216 -0,185 [8,50 dia.]
	0 -0,078	0 -0,0073



Dimensions for Twin-Lock™ valving



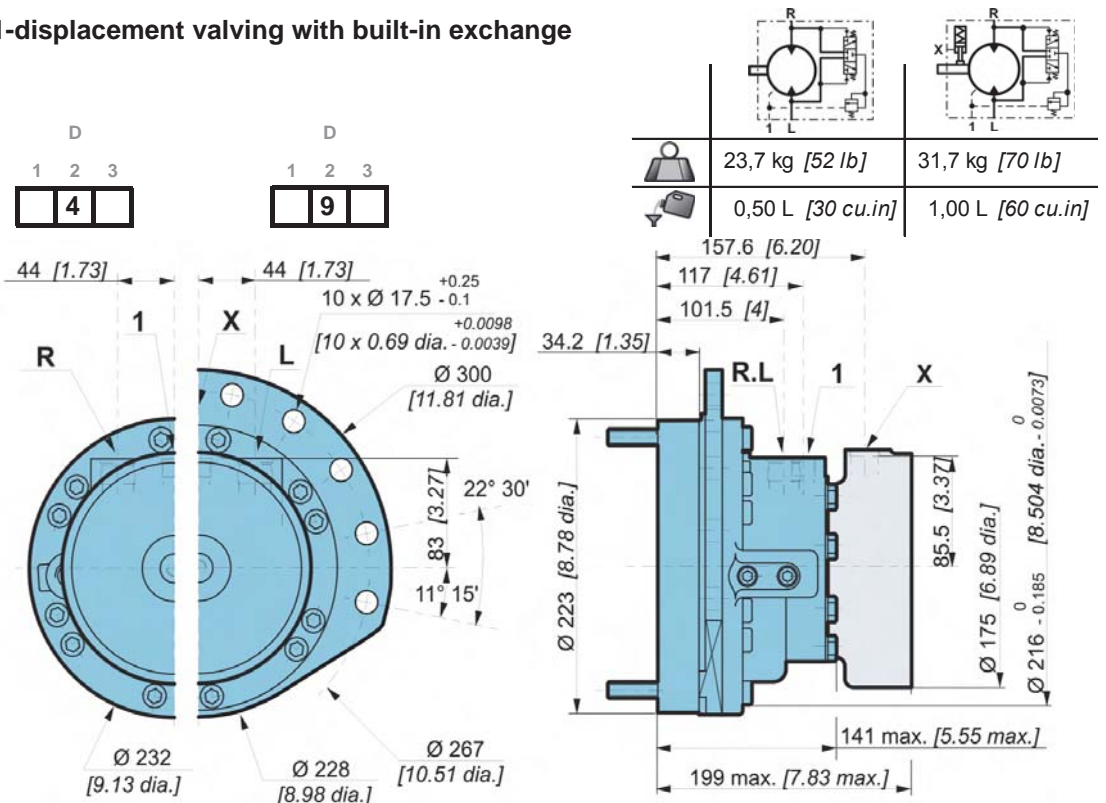
Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Dimensions for 1-displacement valving with built-in exchange



Brake

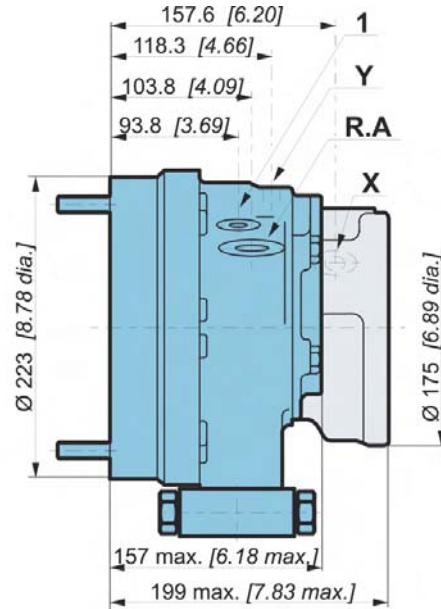
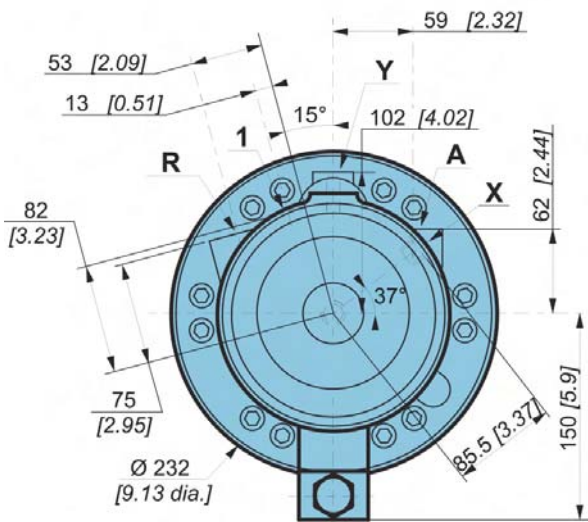
Options



Dimensions for 2-displacement valving with add-on exchange



	27,6 kg [61 lb]	35,2 kg [77 lb]
	0,50 L [30 cu.in]	1,00 L [60 cu.in]



Exchange

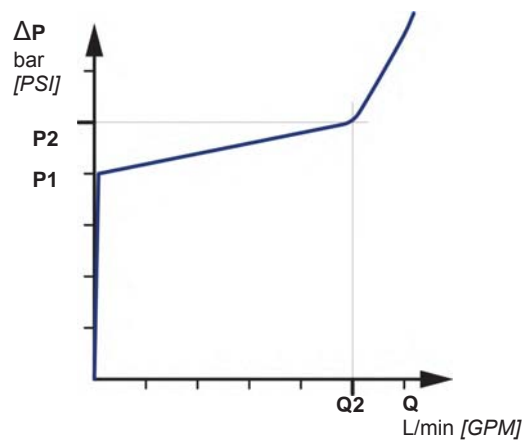
When a coding request is made, you must specify information on the threshold of the selector and the valve.

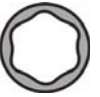
Selector spool

Selector threshold bar [PSI]	Opening pressure of selector bar [PSI]
8 [116]	9.9 ±1.2 [144 ±17]

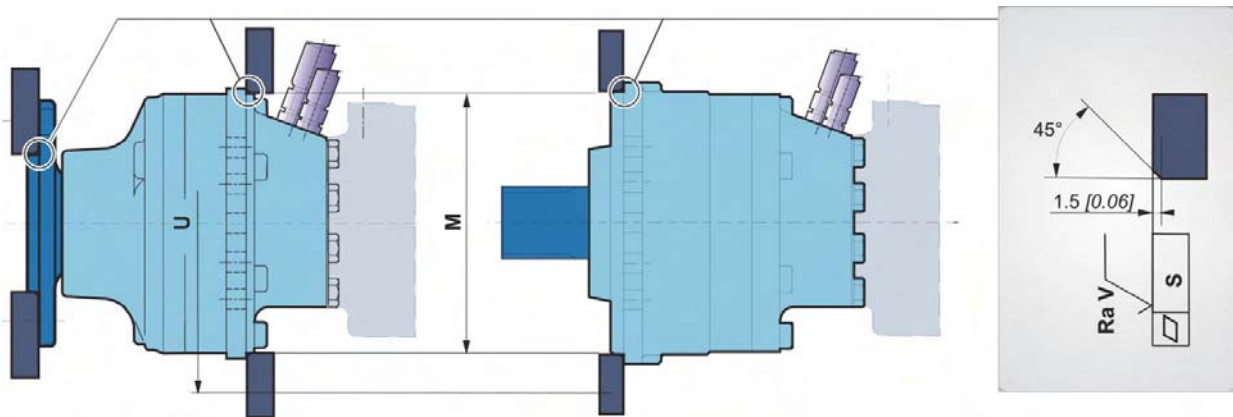
Fitted valve

P1 bar [PSI]	Q2 L/min [GPM]	P2 bar [PSI]
13.5 [195]	14 [3.7]	16 [232]
18 [261]	15 [3.9]	21 [305]
22 [319]	16 [4.2]	25 [363]











Chassis mountings



Take care over the immediate environment of the connections.

MS05 / MSE05	ØM ⁽¹⁾	ØU	S	Ra V		Class	 *
P	200 [7,87]	265 [10,43]	0,2 [0,008]	12,5µm [0,49µin]	2 x 4 M16 x 2	8,8	210 N.m [155 lb.ft]
R 	216 [8,50]	267 [10,51]			10 M16 x 2		
R 	224 [8,82]	265 [10,43]			2 x 4 M16 x 2		
P	200 [7,87]	265 [10,43]			2 x 4 M16 x 2		
R 	216 [8,50]	267 [10,51]			10 M16 x 2		
R 	224 [8,82]	265 [10,43]			2 x 4 M16 x 2		

(1) +0,3 [+0,012]
+0,2 [+0,008]

* : Min. values for torque and load to be transmitted.



See generic installation motors N°801478197L.

Modularity and Model code

Wheel motor

Shaft motor

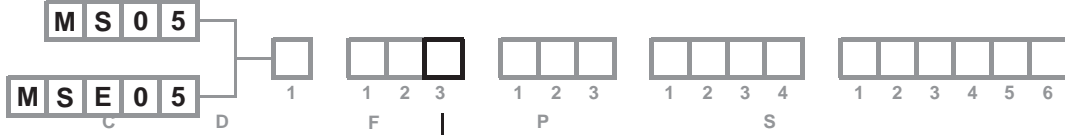
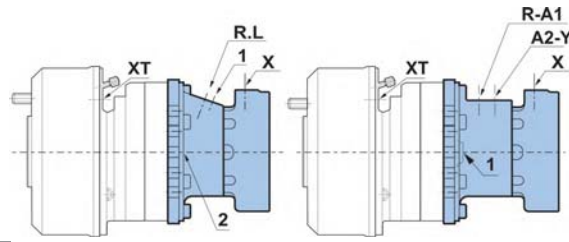
Valving systems and hydrobases

Brake

Options



Hydraulic connections



	Standards	Power supply	Standards	Case drain	2 nd displacement control	Control of parking break	Control of drum break		
		R-L		1, 2		X	XT		
	A	ISO 11 926-1	1"1/16-12 UNF	ISO 11926	3/4"-16 UNF	9/16"-18 UNF	M10x1 (ISO 9974-1)		
	3	ISO 1179	Ø27	ISO 1179	BSP 3/8	BSP 1/4			
	8	ISO 9974-1	M18x1,5	ISO 9974-1	M16x1,5	M14x1,5			
	1*	ISO 6162	SAE 6000PSI 1/2"	ISO 9974-1	M16x1,5	M14x1,5			
	E*	ISO 6162	SAE 6000PSI 1/2"	ISO 9974-1	M16x1,5	M14x1,5			
		R-A		1, 2	Y	X	XT		
	A	ISO 11 926	1"1/16-12 UNF	ISO 11 926	3/4"-16 UNF	3/4"-16 UNF	9/16"-18 UNF	M10x1 (ISO 9974-1)	
	3	ISO 1 179	Ø27	ISO 1179	Ø17	BSP 1/4	BSP 1/4		
	4	ISO 9 974-1	M18x1,5	ISO 9974-1	M16x1,5	M14x1,5	M14x1,5		
	1*	ISO 6162	SAE 6000PSI 1/2"	ISO 9974-1	M16x1,5	M14x1,5	M14x1,5		
		R-A1	A2		1, 2		X	XT	
	A	ISO 11926	1"1/16-12 UNF	3/4"-16 UNF	ISO 11926	3/4"-16 UNF	9/16"-18 UNF	M10x1 (ISO 9974-1)	
	3	ISO 1179	BSP 3/4	BSP 1/2	ISO 1179	BSP 3/8	BSP 1/4		
	4	ISO 9974-1	M27x2	M22x1,5	ISO 9974-1	M16x1,5	M14x1,5		
Max. pressure	MS	bar [PSI]	450 [6 527]	450 [6 527]		1 [15]	30 [435]	30 [435]	120 [1 740]
	MSE	bar [PSI]	400 [5 802]	400 [5 802]					

*only for 1C&2C HighFlow™ valving



You are strongly advised to use the fluids specified in brochure "Installation guide" N° 801478197L.



To find the connections' tightening torques, see the brochure "Installation guide" N° 801478197L.



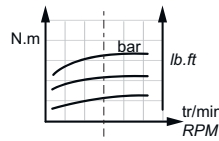
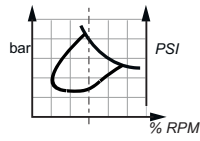
Do not put either a check valve or a poppet valve on the pilot lines (parking brake and displacement change) between the charge pump and the pilot valve. Do not use a piloting valve with integrated check valve.



Efficiency for Classic and HighFlow™ motor

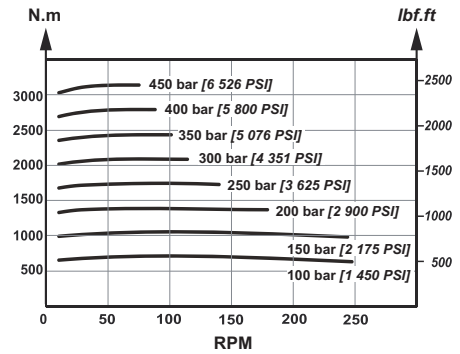
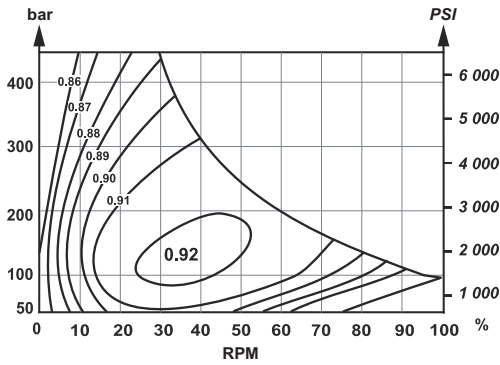
Overall efficiency

Average values given for guidance for code 0 displacement after 100 hours of operation with HV46 hydraulic fluid at 50°C [122°F].

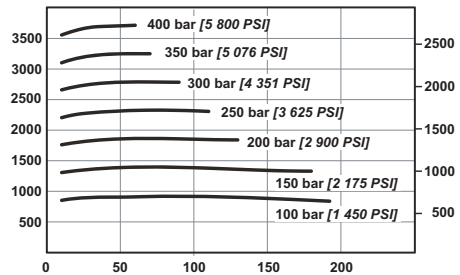
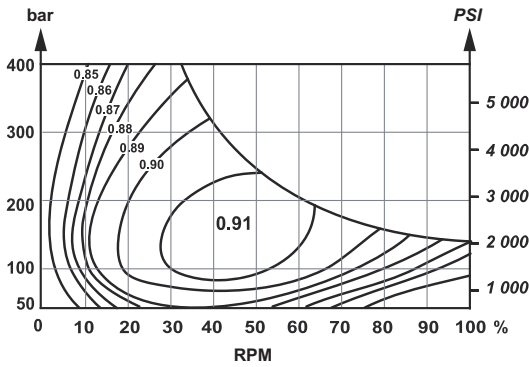


Actual output torque

MS05



MSE05



For a precise calculation, consult your Poclain Hydraulics application engineer.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

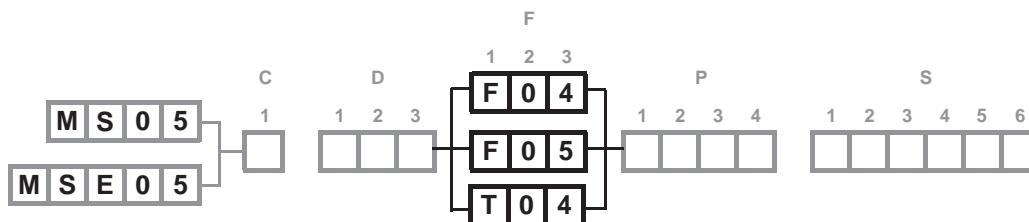
Brake

Options

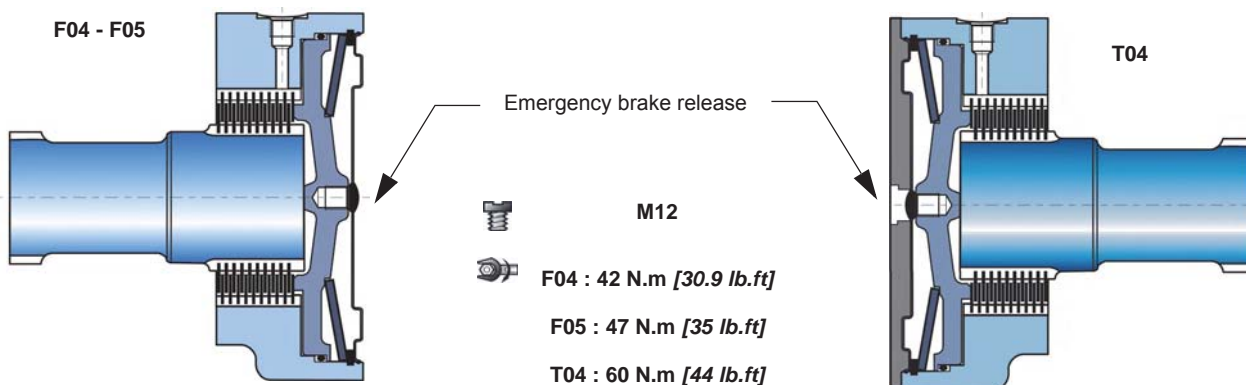




BRAKES



Rear brake



Brake principle

This is a multidisc brake which is activated by a lack of pressure. The spring exerts a force on the piston, which presses on the fixed and mobile discs, and immobilizes the shaft. The braking torque decreases in linear proportion to the brake release pressure.

C	F 0 4	F 0 5	T 0 4
Parking brake torque at 0 bars on housing (new brake)	4 220 Nm [3 110 lb.ft]	3 060 Nm [2 260 lb.ft]	4 220 Nm [3 110 lb.ft]
Dynamic emergency braking torque at 0 bars on housing (max. 10 uses of emergency brakes)	2 740 Nm [2 020 lb.ft]	1 990 Nm [1 470 lb.ft]	2 740 Nm [2 020 lb.ft]
Residual parking braking at 0 bars on housing *	3 165 Nm [2 330 lb.ft]	2 295 Nm [1 690 lb.ft]	3 165 Nm [2 330 lb.ft]
Min. brake release pressure	12 bar [174 PSI]	12 bar [174 PSI]	12 bar [174 PSI]
Max. brake release pressure	30 bar [435 PSI]	30 bar [435 PSI]	30 bar [435 PSI]
Oil capacity	70 cm ³ [4,3 cu.in]	70 cm ³ [4,3 cu.in]	70 cm ³ [4,3 cu.in]
Volume for brake release	32 cm ³ [2,0 cu.in]	32 cm ³ [2,0 cu.in]	32 cm ³ [2,0 cu.in]
Max. energy dissipation	85 902 J		85 902 J

* After emergency brake has been used



Do not run-in the multidisc brakes.



A functional check of the parking brake must be carried out each time it is used as an auxiliary brake (or emergency brake). For all vehicles capable of speeds over 25 km/hour, please contact your Poclain Hydraulics application engineer.



The use of certain oils, may not offer the characteristics stated above. Consult your Poclain Hydraulics sales engineer.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

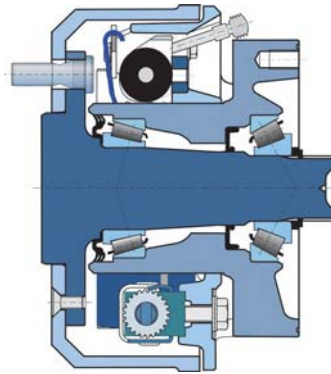
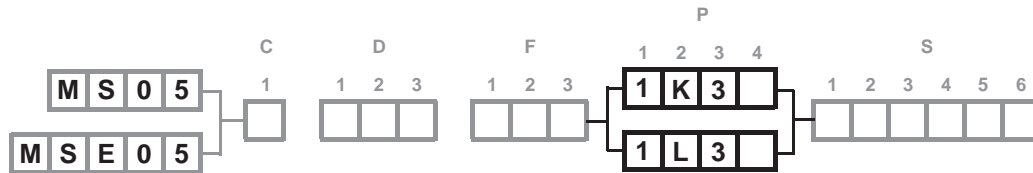
Brake

Options



Drum brake (250 x 60)

Diameter of brake pads : Ø 250 [9.84 dia.]
 Width of friction surface : 60 [2.36]



Brake pads

Asbestos free material	BERAL 1117
Compensation for wear	Automatic

Hydraulically controlled dynamic braking

Max. permissible continuous brake torque	3 000 N.m [2 213 lb.ft]
Pressure to obtain max. permissible continuous brake torque	76 bar [1 102 PSI]
Max. permissible brake torque	5 000 N.m [3 688 lb.ft]
Pressure to obtain max. permissible brake torque	120 bar [1 740 PSI]

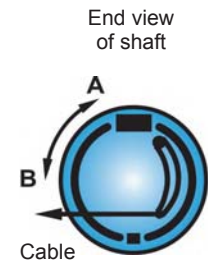
Fluid

Mineral	Yes	K	C
DOT 3/DOT4/SAE J1703	Yes	L	

Max. volume required to bring pads into contact	2,8 cm³ [0,17 cu.in]
---	----------------------

Mechanically controlled parking brake

Max. braking torque	5 000 N.m [3 688 lb.ft]
Max permissible force on the cable	1 370 N [308 lbf]
Force required to bring pads into contact	33 N [7 lbf]
Stroke required to bring pads into contact	A 10,6 mm [0,42 "] B 11,0 mm [0,43 "]
Max. stroke before automatic brake adjustment	A 14,0 mm [0,55 "] B 14,5 mm [0,57 "]



The max. braking torque can only be obtained when the brake has been run in. Consult your Poclain Hydraulics application engineer.

Control

The drum brakes can be controlled hydraulically (service brake) and by a cable (mechanical control for parking brake).



Do not use hydraulic and mechanical brake controls simultaneously.



See also 'Wheel motor' section (thumbnail opposite).

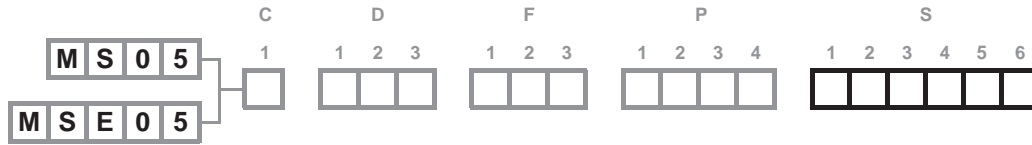


When making an encoding request, you must indicate the following information:

- The material of the brake linings,
- The type of connection at the end of the parking brake control cable,
- Fill out the technical questionnaire for validation of the brake.



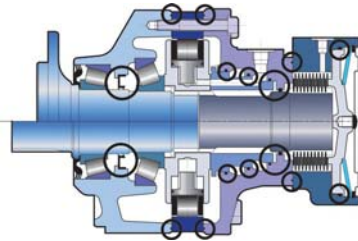
OPTIONS



You can accumulate more than one optional part. Consult your Poclain Hydraulics sales engineer.

1 - Fluorinated elastomer seals

Nitrile seals marked in the figure below replaced by fluorinated elastomer seals.

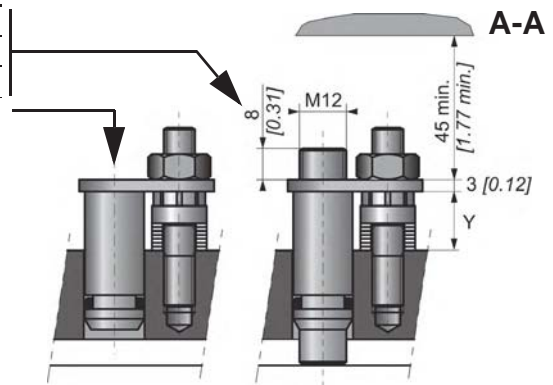
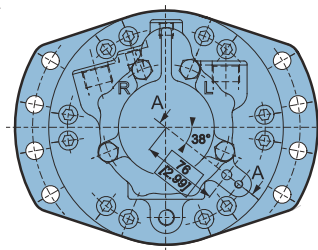
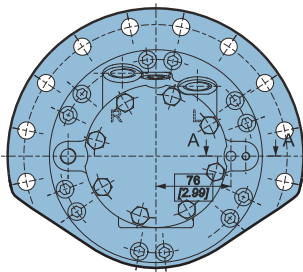


Consult your Poclain Hydraulics sales engineer.

2 - S - Q - 8 - Installed speed sensor or predisposition

Designation

T4 speed sensor (without rotation direction)	2
TR speed sensor (digital rotation direction)	S
TD speed sensor (two phase shifted frequencies)	Q
Predisposition for speed sensor	8



Max. length Y= 20.7

Standard number of pulses per revolution= 56



Look at the "Mobile Electronic" N° A01889D technical catalogue for the sensor specifications and its connection.



To install the sensor, see the "Installation guide" brochure No. 801478197L.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

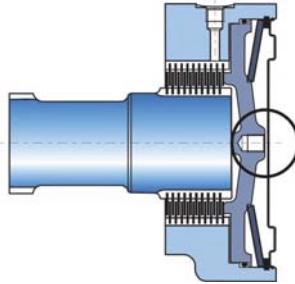
Brake

Options



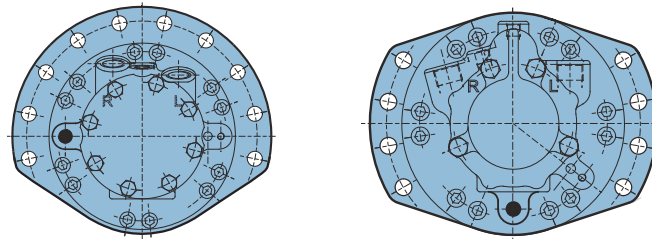
3 - Brake environmental cover without plug

No plug or hole in the cover.
(see figure opposite)



5 - Drainage

Additional drain in the cover.



6 - Industrial support

Reduction of around 50% from the rated value in the bearings' preload value.

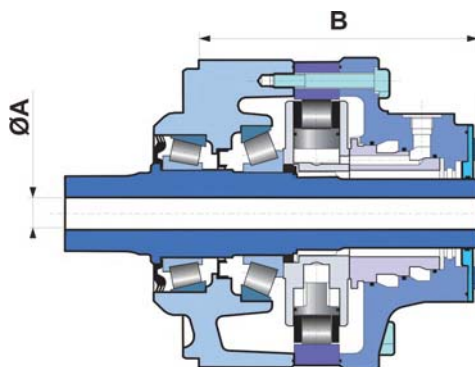


For a precise calculation, consult your Poclain Hydraulics application engineer.

7 - Diamond™

Special treatment of the motor core which considerably increases its strength, making the motor much more tolerant to temporary instances of the operating conditions being exceeded.

A - Hollow shaft

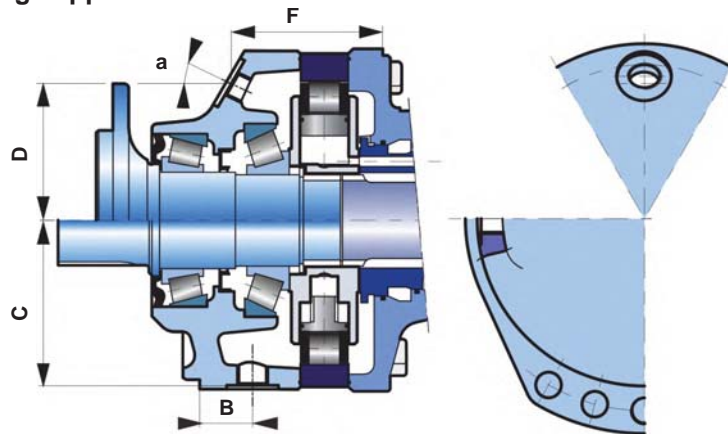


A	B
mm [in]	mm [in]
Ø 25 [0,98 dia.]	214,2 [8,43]

Radial load x 0.75
No torque allowed towards the rear



B - Drain on the bearing support



	BSPB	B	C	D	E	F	a
		mm [in]	mm [in]	mm [in]		mm [in]	
Shaft motor	Ø17	25 [1,0]	111 [4,37]		25°		
Wheel motor	Ø17			87,5 [3,44]		84,0 [3,31]	36°

C - Abrasive environments (mechanical seal)

Some environments can be very harmful. The mirror seal gives reinforced motor sealing.

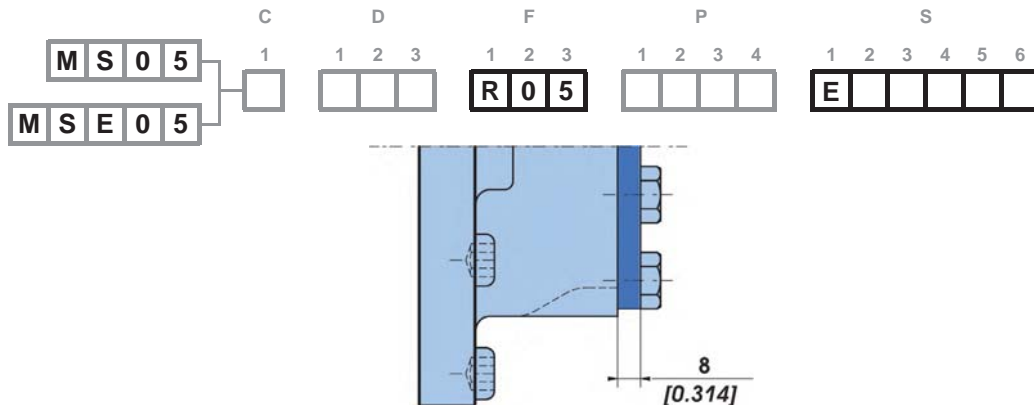
Mechanical seal



Consult your Poclain Hydraulics sales engineer.

E - Reinforced sealing

Reinforced seals and, for an unbraked motor, a rear reinforced plate (R02 - 8 mm thick, instead of 2 mm).



G - Special wheel rim mounting

Enables certain combinations different from the standard mountings defined on page 11 are possible.



Consult your Poclain Hydraulics sales engineer.

H - High efficiency

Reinforced piston sealing to improve volumetric efficiency.



For a precise calculation, consult your Poclain Hydraulics application engineer.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

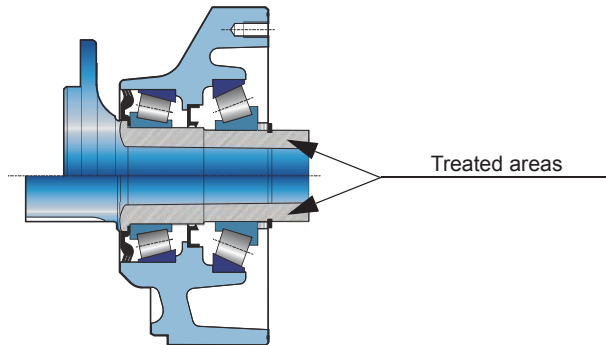
Brake

Options



J - Treated shaft

Heat treatment on the indicated bearing radius and splines.



M - High speed

Under certain conditions, an increase in the maximum speed of 30% above the values indicated in the table on page 2 is possible.



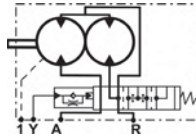
For a precise calculation, consult your Poclain Hydraulics application engineer.



Option "M" becomes mandatory when selecting the HighFlow™ valving.

T - Soft Shift™

Progressive displacement change (cushioned slide-valve)



Consult your Poclain Hydraulics sales engineer.



Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

Brake

Options



Poclain Hydraulics reserves the right to make any modifications it deems necessary to the products described in this document without prior notification. The information contained in this document must be confirmed by Poclain Hydraulics before any order is submitted.

Illustrations are not binding.

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	25/04/2017
	801 478 118A
	801 478 188B
	801 578 101C
	801 578 113Q
	801 578 125D
	A07441N
	Not available
	A14240D

